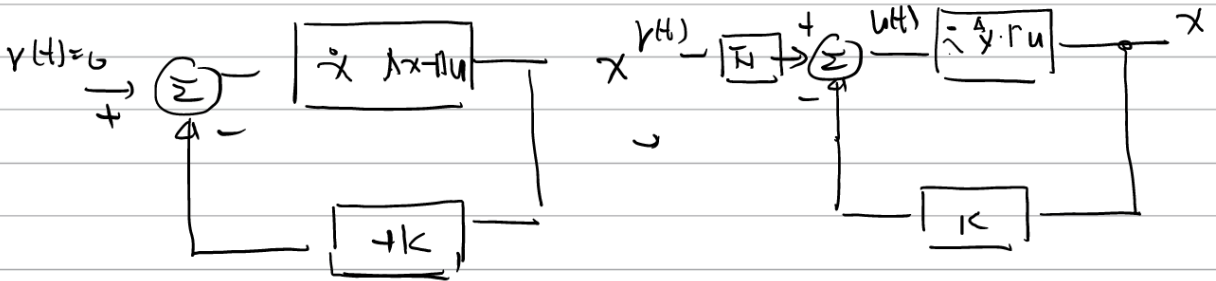




문제 3 Reference input → Output Transfer function

문제 3 문제

Reference input → output.



$u(t) = \bar{u}r - kx$ ← matrix & zero.

$$\dot{x} = Ax + Bu \quad \xrightarrow{u = \bar{u}r - kx} \quad \dot{x} = Ax + B(\bar{u}r - kx)$$

$$\dot{x} - Ax + BKx = B\bar{u}r$$

$$(sI - A + BK)x = B\bar{u}r \quad x(0) = 0$$

$$A = \begin{bmatrix} 0 & 1 \\ 4 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad C = [1, 0] \quad k = [k_1, k_2]$$

$$(sI - A + BK) = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 4 & 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} [k_1, k_2]$$

$[2 \times 1] [1 \times 2] = 2 \times 2$

$$= \begin{bmatrix} s & -1 \\ -4 & s \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ k_1 & k_2 \end{bmatrix} = \begin{bmatrix} s & -1 \\ k_1 - 4 & k_2 + s \end{bmatrix}$$

$$\frac{X}{R} = \begin{bmatrix} s & -1 \\ k_1 - 4 & k_2 + s \end{bmatrix}^{-1} \bar{N}$$

$$\begin{bmatrix} s & -1 \\ k_1 - 4 & k_2 + s \end{bmatrix}^{-1} = \frac{1}{s(k_2 + s) + (k_1 - 4)} \begin{bmatrix} k_2 + s & 1 \\ -k_1 + 4 & s \end{bmatrix}$$

$$[2 \times 2] \times [2 \times 1] = [2 \times 1]$$

$$\begin{bmatrix} k_2 + s & 1 \\ -k_1 + 4 & s \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ s \end{bmatrix}$$

$$\frac{X}{R} = \frac{1}{s(k_2 + s) + k_1 - 4} \begin{bmatrix} 1 \\ s \end{bmatrix} \bar{N}$$

$$Y = CX \rightarrow \bigcirc [1 \ 0] \begin{bmatrix} 1 \\ s \end{bmatrix} \bar{N}$$

$$= \frac{1}{s(k_2 + s) + k_1 - 4} \bar{N}_1$$

$$Y = \left. \begin{matrix} \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + k_2 s + k_1 - 4} \bar{N} \right\} \end{matrix} \right\}$$